
Contents

Part I Location Theory and the Ordered Median Function

1	Mathematical Properties of the Ordered Median Function	3
1.1	Introduction	3
1.2	Motivating Example	4
1.3	The Ordered Median Function	6
1.4	Towards Location Problems	15

Part II The Continuous Ordered Median Location Problem

2	The Continuous Ordered Median Problem	23
2.1	Problem Statement	23
2.2	Distance Functions	27
2.2.1	The Planar Case	31
2.3	Ordered Regions, Elementary Convex Sets and Bisectors	34
2.3.1	Ordered Regions	34
2.3.2	Ordered Elementary Convex Sets	35
2.3.3	Bisectors	39
3	Bisectors	43
3.1	Bisectors - the Classical Case	43
3.2	Possible Generalizations	44
3.3	Bisectors - the General Case	46
3.3.1	Negative Results	47
3.3.2	Structural Properties	48
3.3.3	Partitioning of Bisectors	59
3.4	Bisectors of Polyhedral Gauges	65
3.5	Bisectors of Elliptic Gauges	74
3.6	Bisectors of a Polyhedral Gauge and an Elliptic Gauge	83
3.7	Approximation of Bisectors	96

4	The Single Facility Ordered Median Problem	105
4.1	Solving the Single Facility OMP by Linear Programming	105
4.2	Solving the Planar Ordered Median Problem Geometrically	110
4.3	Non Polyhedral Case	117
4.4	Continuous OMPs with Positive and Negative Lambdas	123
4.4.1	The Algorithms	127
4.5	Finding the Ordered Median in the Rectilinear Space	134
5	Multicriteria Ordered Median Problems	137
5.1	Introduction	137
5.2	Multicriteria Problems and Level Sets	138
5.3	Bicriteria Ordered Median Problems	139
5.4	The 3-Criteria Case	151
5.5	The Case $Q > 3$	158
5.6	Concluding Remarks	162
6	Extensions of the Continuous Ordered Median Problem	165
6.1	Extensions of the Single Facility Ordered Median Problem	165
6.1.1	Restricted Case	165
6.2	Extension to the Multifacility Case	169
6.2.1	The Non-Interchangeable Multifacility Model	170
6.2.2	The Indistinguishable Multifacility Model	172
6.3	The Single Facility OMP in Abstract Spaces	174
6.3.1	Preliminary Results	176
6.3.2	Analysis of the Optimal Solution Set	185
6.3.3	The Convex OMP and the Single Facility Location Problem in Normed Spaces	189
6.4	Concluding Remarks	193

Part III Ordered Median Location Problems on Networks

7	The Ordered Median Problem on Networks	197
7.1	Problem Statement	197
7.2	Preliminary Results	200
7.3	General Properties	203
8	On Finite Dominating Sets for the Ordered Median Problem	209
8.1	Introduction	209
8.2	FDS for the Single Facility Ordered Median Problem	210
8.3	Polynomial Size FDS for the Multifacility Ordered Median Problem	214
8.3.1	An FDS for the Multifacility Ordered Median Problem when $a = \lambda_1 = \dots = \lambda_k \neq \lambda_{k+1} = \dots = \lambda_M = b$	215

8.3.2 An FDS for the Ordered 2-Median Problem with General Nonnegative λ -Weights	225
8.4 On the Exponential Cardinality of FDS for the Multifacility Facility Ordered Median Problem.....	236
8.4.1 Some Technical Results	239
8.4.2 Main Results	245
9 The Single Facility Ordered Median Problem on Networks 249	
9.1 The Single Facility OMP on Networks: Illustrative Examples ..	250
9.2 The k -Centrum Single Facility Location Problem	254
9.3 The General Single Facility Ordered Median Problem on Networks	266
9.3.1 Finding the Single Facility Ordered Median of a General Network	267
9.3.2 Finding the Single Facility Ordered Median of a Tree ..	269
10 The Multifacility Ordered Median Problem on Networks .. 275	
10.1 The Multifacility k -Centrum Problem	275
10.2 The Ordered p -Median Problem with λ^s -Vector $\lambda^s = (a, M^{-s}, a, b, \dots, b)$	281
10.3 A Polynomial Algorithm for the Ordered p -Median Problem on Tree Networks with λ^s -Vector, $\lambda^s = (a, M^{-s}, a, b, \dots, b)$..	283
11 Multicriteria Ordered Median Problems on Networks 289	
11.1 Introduction	289
11.2 Examples and Remarks	291
11.3 The Algorithm	293
11.4 Point Comparison	295
11.5 Segment Comparison	296
11.6 Computing the Set of Efficient Points Using Linear Programming	307
12 Extensions of the Ordered Median Problem on Networks .. 311	
12.1 Notation and Model Definitions	312
12.2 Tactical Subtree with Convex Ordered Median Objective ..	314
12.2.1 Finding an Optimal Tactical Subedge	314
12.2.2 Finding an Optimal Tactical Continuous Subtree Containing a Given Node.....	315
12.3 Strategic Subtree with Convex Ordered Median Objective ..	317
12.3.1 Finding an Optimal Strategic Subedge	318
12.3.2 Finding an Optimal Strategic Continuous Subtree Containing a Given Node.....	318
12.3.3 Submodularity of Convex Ordered Median Functions ..	318
12.4 The Special Case of the Subtree k -Centrum Problem	320

12.4.1	Nestedness Property for the Strategic and Tactical Discrete k -Centrum Problems	321
12.4.2	A Dynamic Programming Algorithm for the Strategic Discrete Subtree k -Centrum Problem	322
12.5	Solving the Strategic Continuous Subtree k -Centrum Problem .	325
12.6	Concluding Remarks	327

Part IV The Discrete Ordered Median Location Problem

13	Introduction and Problem Statement	331
13.1	Definition of the Problem	332
13.2	A Quadratic Formulation for the Discrete OMP	335
13.2.1	Sorting as an Integer Linear Program (ILP)	336
13.2.2	Formulation of the Location-Allocation Subproblem . .	337
13.2.3	Quadratic Integer Programming Formulation for OMP .	339
14	Linearizations and Reformulations	341
14.1	Linearizations of (OMP)	341
14.1.1	A First Linearization: (OMP ¹)	341
14.1.2	A Linearization Using Less Variables: (OMP ²) . .	346
14.1.3	Simplifying Further: (OMP ³)	349
14.1.4	Comparison Between (OMP ²) and (OMP ³)	352
14.2	Reformulations	354
14.2.1	Improvements for (OMP ¹)	356
14.2.2	Improvements for (OMP ³)	362
14.2.3	Improvements for (OMP ²)	368
14.2.4	Comparison Between (OMP ^{2*}) and (OMP ^{3*}) . . .	371
14.3	Computational Results	372
15	Solution Methods	381
15.1	A Branch and Bound Method	381
15.1.1	Combinatorial Lower Bounds	382
15.1.2	Branching	387
15.1.3	Numerical Comparison of the Branching Rules	389
15.1.4	Computational Results	390
15.2	Two Heuristic Approaches for the OMP	393
15.2.1	An Evolution Program for the OMP	393
15.2.2	A Variable Neighborhood Search for the OMP	399
15.2.3	Computational Results	407
16	Related Problems and Outlook	419
16.1	The Discrete OMP with $\lambda \in \Lambda_M^{\leq}$	419
16.1.1	Problem Formulation	419
16.1.2	Computational Results	421

16.2 Conclusions and Further Research	422
References	423
Index	435