

Table of Contents

Effective Algorithms for a Class of Discrete Valued Optimal Control Problems	1
<i>Louis Caccetta, Ian van Loosen, and Volker Rehbock</i>	
Minimum Time Multi-UGV Surveillance	31
<i>David Anisi and Petter Ögren</i>	
A Distributed Network Enabled Weapon-Target Assignment for Combat Formations	47
<i>N. Léchevin, C.A. Rabbath, and M. Lauzon</i>	
Simultaneous Localization and Planning for Cooperative Air Munitions Via Dynamic Programming	69
<i>Emily A. Doucette, Andrew J. Sinclair, and David E. Jeffcoat</i>	
A New Multi-objective Control Design for Autonomous Vehicles	81
<i>Jiangmin Chunyu, Zhihua Qu, Eytan Pollak, and Mark Falash</i>	
Maximizing Search Coverage Using Future Path Projection for Cooperative Multiple UAVs with Limited Communication Ranges	103
<i>Pedro DeLima and Daniel Pack</i>	
Operator Aided Decision Processes for UAVs in a Stochastic Environment	119
<i>John J. Baker, Raymond Holsapple, Anouck Girard, Meir Pachter, and Phillip Chandler</i>	
Dynamics and Control of Surface Exploration Robots on Asteroids	135
<i>Julie Bellerose, Anouck Girard, and Daniel J. Scheeres</i>	
Trajectory Generation for Relative Guidance of Merging Aircraft	151
<i>Félix Mora-Camino, Karim Achaibou, and Baba Ouattara</i>	
A Comparative Study of Task Assignment and Path Planning Methods for Multi-UGV Missions	167
<i>Johan Thunberg, David A. Anisi, and Petter Ögren</i>	
Optimal Control of the Weapon Operating Characteristic with Control Inequality Constraints	181
<i>John Bode II, David Jacques, and Meir Pachter</i>	
Autonomous Target Detection and Localization Using Cooperative Unmanned Aerial Vehicles	195
<i>Youngrock Yoon, Scott Gruber, Lucas Krakow, and Daniel Pack</i>	

VIII Table of Contents

Cooperative Control of Multiple Swarms of Mobile Robots with Communication Constraints	207
<i>Yechiel J. Crispin</i>	
Towards Optimal Positioning of Surveillance UGVs	221
<i>Ulrik Nilsson, Petter Ögren, and Johan Thunberg</i>	
The Maximum Weight Independent Set Problem for Data Association in Multiple Hypothesis Tracking	235
<i>Dimitri J. Papageorgiou and Michael R. Salpukas</i>	
New Results in Stochastic Cooperative Games: Strategic Coordination for Multi-resolution Performance Robustness	257
<i>Khanh D. Pham</i>	
Switching among Solvers: Collaborative Algorithms with Parameter Control	287
<i>Carlos Castro and María Cristina Riff</i>	
An Event-Driven Software Architecture for Multiple Unmanned Aerial Vehicles to Cooperatively Locate Mobile Targets	299
<i>Dimitri Zarchitsky, Marc Schlegel, Andreas Decker, and Daniel Pack</i>	
Robust Track Association and Fusion with Extended Feature Matching	319
<i>Huimin Chen, Genshe Chen, Erik P. Blasch, and Tod M. Schuck</i>	
Optimal Cooperative Thermalling of Unmanned Aerial Vehicles	355
<i>Andrew T. Klesh, Pierre T. Kabamba, and Anouck R. Girard</i>	
Model Predictive Control of Vehicle Formations	371
<i>Fernando A.C.C. Fontes, Dalila B.M.M. Fontes, and Amélia C.D. Caldeira</i>	
Application of Monkey Search Meta-heuristic to Solving Instances of the Multidimensional Assignment Problem	385
<i>Alla R. Kammerdiner, Antonio Mucherino, and Panos M. Pardalos</i>	
Robust Wireless Network Jamming Problems	399
<i>Clayton W. Commander, Panos M. Pardalos, Valeriy Ryabchenko, Sergey Sarykalin, Timofey Turko, and Stan Uryasev</i>	
A Token-Based Approach to Sharing Beliefs in a Large Multiagent Team	417
<i>Prasanna Velagapudi, Oleg Prokopyev, Paul Scerri, and Katia Sycara</i>	
Development of a Mission Simulator for Design and Testing of C2 Algorithms and HMI Concepts across Real and Virtual Manned-Unmanned Fleets	431
<i>Oktay Arslan, Bahadır Armagan, and Gokhan Inalhan</i>	
Author Index	459